

## Single Phase Half Controlled Bridges

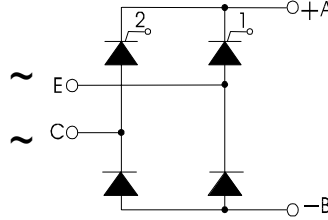
### PSBH 85

$I_{dAV}$  = 82 A  
 $V_{RRM}$  = 400-1600 V

Preliminary Data Sheet

| $V_{RSM}$<br>$V_{DSM}$ | $V_{RRM}$<br>$V_{DRM}$ | Type       |
|------------------------|------------------------|------------|
| 500                    | 400                    | PSBH 85/04 |
| 900                    | 800                    | PSBH 85/08 |
| 1300                   | 1200                   | PSBH 85/12 |
| 1500                   | 1400                   | PSBH 85/14 |
| *1700                  | *1600                  | PSBH 85/16 |

\* Delivery on request



| Symbol             | Test Conditions   | Maximum Ratings                |
|--------------------|---|--------------------------------|
| $I_{dAV}$          | $T_C = 85^\circ\text{C}$ per module   | 82 A                           |
| $I_{FSM}, I_{TSM}$ | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0$<br>$t = 10\text{ ms}$ (50 Hz), sine  | 1150 A                         |
|                    | $t = 8.3\text{ ms}$ (60 Hz), sine   | 1230 A                         |
|                    | $T_{VJ} = T_{VJM}$<br>$V_R = 0$<br>$t = 10\text{ ms}$ (50 Hz), sine   | 1000 A                         |
|                    | $t = 8.3\text{ ms}$ (60 Hz), sine   | 1070 A                         |
| $\int i^2 dt$      | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0$<br>$t = 10\text{ ms}$ (50 Hz), sine  | 6600 $\text{A}^2\text{ s}$     |
|                    | $t = 8.3\text{ ms}$ (60 Hz), sine   | 6280 $\text{A}^2\text{ s}$     |
|                    | $T_{VJ} = T_{VJM}$<br>$V_R = 0$<br>$t = 10\text{ ms}$ (50 Hz), sine   | 5000 $\text{A}^2\text{ s}$     |
|                    | $t = 8.3\text{ ms}$ (60 Hz), sine   | 4750 $\text{A}^2\text{ s}$     |
| $(di/dt)_{cr}$     | $T_{VJ} = T_{VJM}$ repetitive, $I_T = 50\text{ A}$<br>$f = 400\text{ Hz}$ , $t_p = 200\mu\text{s}$<br>$V_D = 2/3 V_{DRM}$ | 150 $\text{A}/\mu\text{s}$     |
|                    | $I_G = 0.3\text{ A}$ non repetitive, $I_T = 1/3 \cdot I_{dAV}$<br>$di_G/dt = 0.3\text{ A}/\mu\text{s}$                    | 500 $\text{A}/\mu\text{s}$     |
| $(dv/dt)_{cr}$     | $T_{VJ} = T_{VJM}$ $V_{DR} = 2/3 V_{DRM}$<br>$R_{GK} = \infty$ , method 1 (linear voltage rise)                           | 1000 $\text{V}/\mu\text{s}$    |
| $P_{GM}$           | $T_{VJ} = T_{VJM}$ $t_p = 30\mu\text{s}$  | $\leq 10\text{ W}$             |
|                    | $I_T = I_{TAVM}$ $t_p = 500\mu\text{s}$   | $\leq 5\text{ W}$              |
| $P_{GAVM}$         |   | 0.5 W                          |
| $V_{RGM}$          |   | 10 V                           |
| $T_{VJ}$           |   | -40 ... + 125 $^\circ\text{C}$ |
| $T_{VJM}$          |   | 125 $^\circ\text{C}$           |
| $T_{stg}$          |   | -40 ... + 125 $^\circ\text{C}$ |
| $V_{ISOL}$         | 50/60 HZ, RMS $t = 1\text{ min}$  | 2500 V ~                       |
|                    | $I_{ISOL} \leq 1\text{ mA}$ $t = 1\text{ s}$  | 3000 V ~                       |
| $M_d$              | Mounting torque (M6)  | 5 Nm                           |
|                    | Terminal connection torque (M6)   | 5 Nm                           |
| Weight             | typ.  | 270 g                          |

### Features

- Package with screw terminals
- Isolation voltage 3000 V~
- Planar glasspassivated chips
- Low forward voltage drop
- UL released, E 148688

### Applications

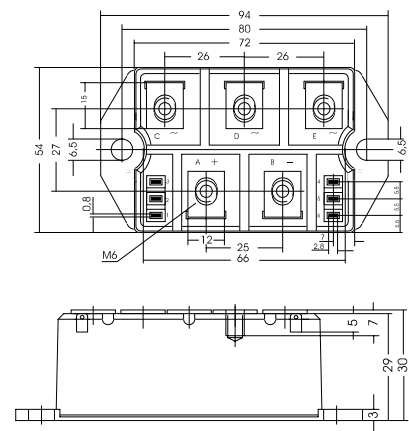
- Heat and temperature control for industrial furnaces and chemical processes
- Lighting control
- Motor control
- Power converter

### Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling capability
- High power density

### Package, style and outline

Dimensions in mm (1mm = 0.0394")



| Symbol     | Test Conditions  | Characteristic Value   |        |                  |    |
|------------|--|------------------------|--------|------------------|----|
| $I_D, I_R$ | $T_{VJ} = T_{VJM}, V_R = V_{RRM}, V_D = V_{DRM}$           | $\leq$                 | 5      | mA               |    |
| $V_T$      | $I_T = 200A, T_{VJ} = 25^\circ C$                          | $\leq$                 | 1.75   | V                |    |
| $V_{TO}$   | For power-loss calculations only ( $T_{VJ} = T_{VJM}$ )    |                        | 0.85   | V                |    |
| $r_T$      |  |                        | 6      | m $\Omega$       |    |
| $V_{GT}$   | $V_D = 6V$   | $T_{VJ} = 25^\circ C$  | $\leq$ | 1.5              | V  |
|            |  | $T_{VJ} = -40^\circ C$ | $\leq$ | 1.6              | V  |
| $I_{GT}$   | $V_D = 6V$   | $T_{VJ} = 25^\circ C$  | $\leq$ | 100              | mA |
|            |  | $T_{VJ} = -40^\circ C$ | $\leq$ | 200              | mA |
| $V_{GD}$   | $T_{VJ} = T_{VJM}, V_D = 2/3 V_{DRM}$                      | $\leq$                 | 0.2    | V                |    |
| $I_{GD}$   | $T_{VJ} = T_{VJM}, V_D = 2/3 V_{DRM}$                      | $\leq$                 | 5      | mA               |    |
| $I_L$      | $T_{VJ} = 25^\circ C, t_p = 30\mu s$                       | $\leq$                 | 450    | mA               |    |
|            | $I_G = 0.3A, di_G/dt = 0.3A/\mu s$                         |                        |        |                  |    |
| $I_H$      | $T_{VJ} = 25^\circ C, V_D = 6V, R_{GK} = \infty$           | $\leq$                 | 200    | mA               |    |
| $t_{gd}$   | $T_{VJ} = 25^\circ C, V_D = 1/2 V_{DRM}$                   | $\leq$                 | 2      | $\mu s$          |    |
|            | $I_G = 0.3A, di_G/dt = 0.3A/\mu s$                         |                        |        |                  |    |
| $t_q$      | $T_{VJ} = T_{VJM}, I_T = 20A, t_p = 200\mu s, V_R = 100V$  |                        | 150    | $\mu s$          |    |
|            | $-di/dt = 10A/\mu s, dv/dt = 15V/\mu s, V_D = 2/3 V_{DRM}$ |                        |        |                  |    |
| $R_{thJC}$ | per thyristor; sine 180°el                                 |                        | 0.65   | K/W              |    |
|            | per module   |                        | 0.1625 | K/W              |    |
| $R_{thJK}$ | per thyristor; sine 180° el                                |                        | 0.8    | K/W              |    |
|            | per module   |                        | 0.2    | K/W              |    |
| $d_s$      | Creeping distance on surface                               |                        | 10.0   | mm               |    |
| $d_A$      | Creeping distance in air                                   |                        | 9.4    | mm               |    |
| $a$        | Max. allowable acceleration                                |                        | 50     | m/s <sup>2</sup> |    |

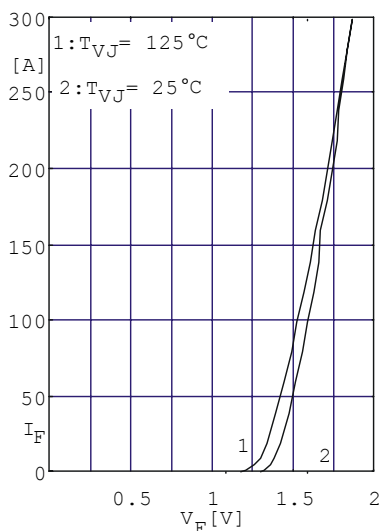


Fig. 1 Forward current vs. voltage drop per diode or thyristor

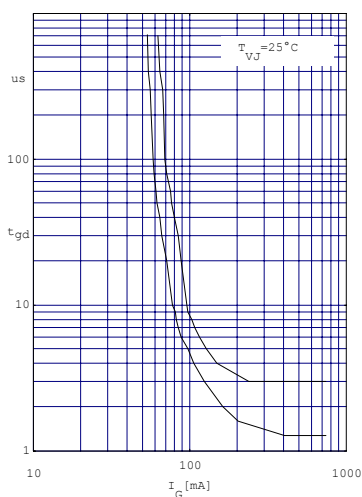


Fig. 2 Gate trigger delay time

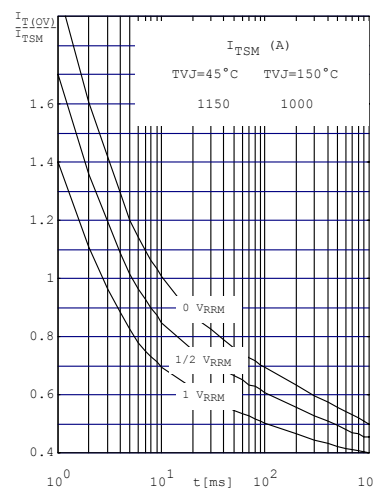


Fig. 3 Surge overload current per diode (or thyristor)  $I_{FSM}$ ,  $I_{TSM}$ : Crest value t: duration

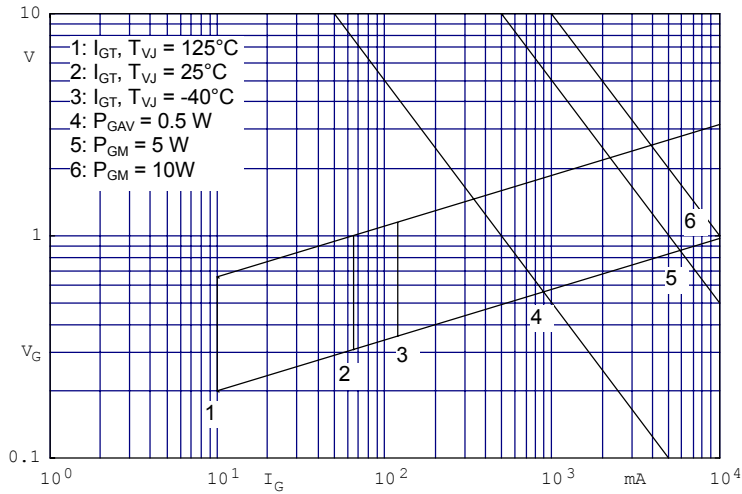


Fig.4 Gate trigger characteristic

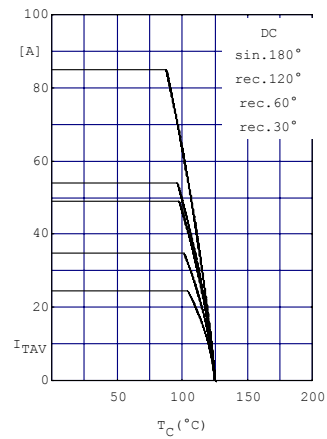


Fig.5 Maximum forward current at case temperature

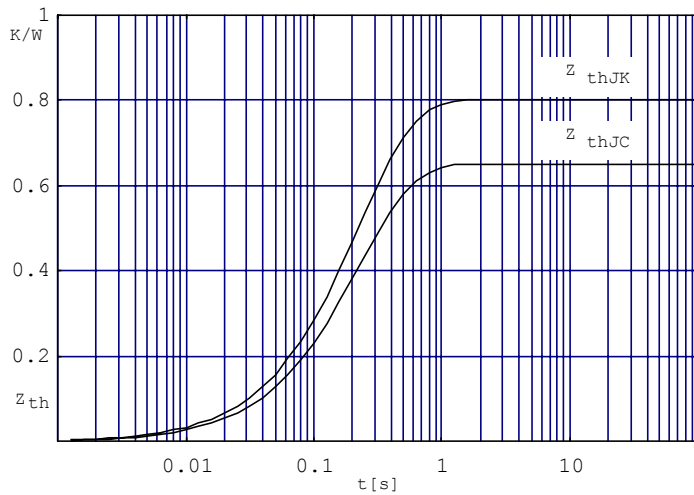


Fig.6 Transient thermal impedance per thyristor or diode (calculated)

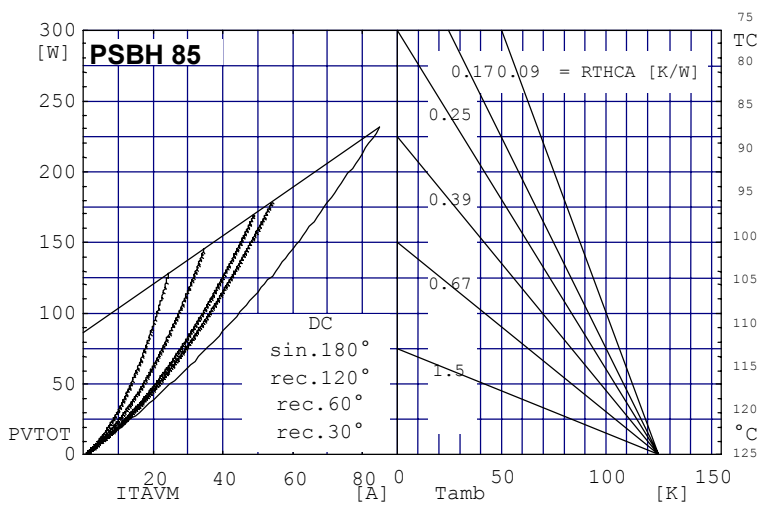


Fig. 7 Power dissipation vs. direct output current and ambient temperature